#### Program Begin and End

	Begin	Beginning of program, required as the first command in every Inventor program.
	End	End of program, required as the last command in every Inventor program.
A	Stop A	Stop Power to RCX Port A.
вс	Stop All Outputs	Stop Power to RCX Ports A, B, C.
	Stop Outputs	Stop Power to specified RCX Ports, default - Ports A, B, C.

#### **Specific Outputs**

A	Motor A, Forward	Turn RCX Port A on in forward direction at full power.
	Motor A, Reverse	Turn RCX Port A on in reverse direction at full power.
	Lamp A	Turn RCX Port A on full power.
	Play Sound #4	Play a rising sweep on the RCX.

#### **General Outputs**

No.	Lamp	Turn lamp on, default – all Po	orts, power level 5.
	Motor Forward	Turn motor on, default – all F	Ports, power level 5.
	Motor Reverse	Turn motor on in reverse dire	ection, default – all Ports, power level 5.
<b>*</b>	Flip Direction	Flip direction of power to spe	ecified RCX Ports, default - all Ports.
<b>₽</b> °	Play Sound	Play a sound on the RCX. The 1-Key Click 2-BeepBeep 5 3-Descending Sweep 6	e sounds available are: 4-Rising Sweep (default setting) 5-Buzz 5-Fast Rising Sweep
	Float Outputs	Stops power to output Ports	and allows devices to spin to a stop.



#### Wait For?

?	Wait For? Sub-menu	Icons in this sub-menu specify when the command icons should stop executing.
13	Wait for 1 Second	Wait 1 second before continuing.
<b>?</b>	Wait for Time	Wait for specified amount of time, default - 1 second.
	Wait Random Time	Wait for a random amount of time, default - between 0 and 5 seconds.
	Wait for Push	Wait until touch sensor is pushed in, default - input Port 1.
R	Wait for Let Go	Wait until touch sensor is released, default - input Port 1.
	Wait for Light	Wait until light sensor reads a value that is brighter than the number specified, default = 55, input Port 1.
	Wait for Dark	Wait until light sensor reads a value that is darker than the number specified, default = 55, input Port 1.
<mark>+</mark> ♥	Wait for Brighter	Wait for light sensor to read a value that is greater than current value. Default - input Port 1, light value increase of 5.
	Wait for Darker	Wait for light sensor to read a value that is less than current value. Default $$ - input Port 1, light value decrease of 5.
	Wait for Rotation Without Reset	Wait until the Angle Sensor value is greater than the number of rotations specified (in 16ths of a rotation) in either direction. This program will not zero the sensor each time.
1 <sup>00</sup>	Wait for Increase in Camera Sensor	Wait until the Camera Sensor reads a value that is greater than the number specified.
1 O	Wait for Decrease in Camera Sensor	Wait until the Camera Sensor reads a value that is less than the number specified.
	Wait for Increasing Temp (C)	Wait until the temperature is greater than the number specified. Default - 30 Celsius on input Port 1.
	RCX Wait for Rotation	Wait until the angle sensor value is greater than the number of rotations specified. Default - 16 (one rotation) on input Port 1.
	Wait for Angle	Wait until the angle sensor value is greater than the angle specified (in either direction). Default - 180 degrees on input Motor 1.
?	Wait for Container	Wait until the container is equal to the number specified. Default - red container equal to 1.
Q	Wait for Timer	Wait until the timer reaches a specified value. Default - red timer equal to 1 second. YOU MUST ZERO TIMER FIRST!
5	Wait for Mail	Wait until mail received from another RCX is equal to the specified number. Default - any whole number.

#### **Reference** List lcon

#### Modifiers

<b>A</b>	Modifiers Sub-menu	Icons in this sub-menu specify port locations, power levels, and values used with the command icons.
	Input 1	Wire this modifier to a command to select input Port 1.
	Output A	Wire this modifier to a command to select output Port A.
	Power Level 4	Wire this modifier into a motor or lamp to set the power level to 4.
123	Numeric Constant	Wire this modifier into a sensor or time to set a constant value.
	Value of Red Container	The value of red container.
$\bigcirc$	Red Container	Wire this to a container command to select red container.
	Random Number	A random number between 0 and 8.
	Value of Port 1	The value of Port 1.
	Red Timer	Wire this to a timer command to select red timer.
۲	Value of Red Timer	The value of red timer.
¢	Value of Mail	The value of the mail.
$\diamond$	Value of Firmware	The value is the firmware version number multiplied by 100.
	Value of Battery	The value is the battery voltage number multiplied by 1000.

Music

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Music Sub-menu	Icons in this sub-menu specify how musical notes should be played.
Music Note C	Play musical note on the RCX. Default - quarter note in the standard scale.
Rest	Insert a pause in the music.
Musical Duration	Specify the length of time for a note to play.
Up an Octave	Wire to a music command to raise the pitch by one octave or more octaves, if more than one is wired together.





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Load Scroll This routine will add the musical notes currently in a file into your inventor program. from File

#### Structures – Jump and Land

-	Jumps Sub-menu	Icons in this sub-menu specify where the program will jump and land in the program.
-	Jump	Make the program jump to a specific place in the string.
-	Land	This command is where the program will jump to when you use red jump command.

Structures – Loops

	Loops Sub-menu	Icons in this sub-menu specify where the program loops will begin and end.
	Start of Loop	Start a loop structure. Default - loop twice.
	End of Loop	Jump back to start of loop a specified number of times.
e de la companya de l	Touch Loop	Start a loop that repeats while the Touch Sensor is pushed.
Ø	Loop While Camera Sensor is Greater Than	Starts a loop that repeats while the value of the camera sensor is greater than a specified number.
Ø	Loop While Camera Sensor is Less Than	Starts a loop that repeats while the value of the camera sensor is less than a specified number.
Structure	es – Forks and Tasks	
	Task Split	Start a new task with this command to run multiple tasks simultaneously

	Task Split	Start a new task with this command to run multiple tasks simultaneously.
	Forks Sub-menu	Icons in this sub-menu specify where the program will choose between two paths and where it will merge again.
en⇒ en÷	Touch Sensor Fork	Have the program choose between one of the two paths depending on the state of touch sensor. Default input Port 1.
	Fork Merge	Merge the two strings of a fork back together. It must be used with a fork.
<u>⊘</u> _	Camera Sensor Fork	Choose a path depending on whether the value of the Camera Sensor is greater-than or less-than a specified number. If the camera sensor is greater than the specified value, the program will follow the top string. If the camera sensor is less than the specified value, the program will follow the bottom string.
2 ?	Random Fork	Have the program choose between one of two paths randomly.

#### **Structures - Subroutines**

	Create Subroutine	Create a new subroutine. The subroutine will not run at this point in the program. It will run when the program reaches the Run Subroutine icon.
	Run Subroutine	Specify where to run the subroutine in the program.
7	Delete Subroutine	Delete the specified subroutines in the RCX. Default is to delete subroutine 0.

#### Container

	Container Sub-menu	Icons in this sub-menu manipulate containers (variables) and the values within them.
	Add to Container	Add a number to container. Default - add 1 to red container.
<b>F</b>	Remove from Container	Subtract a number from container. Default - subtract 1 from red container.
	Fill Container	Set container to a certain value. Default - set red container to 1.
	Touch Container	Set container to the value of touch sensor.
ð	Timer Value Container	Set container to the value of the timer. Default - set red container to value of red timer.
	Formula Container	Set the container to a formula.
	Event State Container	Set the container to a certain event state. Tells whether the event is in the low, normal or high state depending on the set thresholds.
	Event Register Container	Set the container to a copy of the bit register of the successful event(s) for the current task.
	Camera Sensor Container	Set the container to a certain value.

#### Reset

ø	Reset Sub-menu	Icons in this sub-menu reset containers, timers, and sensors to zero.
Ø	Empty Container	Reset container value to zero. Default - set red container to zero.
Ø	Zero Timer	Reset the timer value to zero. Default - set red timer to zero.
	Zero Angle Sensor	Reset the angle sensor to zero. Default - input Port 1.





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2	Empty Mailbox	Reset RCX mailbox value to zero. This empties the mailbox so the mail can be received from another RCX.
Ŷ	Zero Touch Sensor	Reset the touch sensor.
	Zero Light Sensor	Reset the light sensor.
S °C	Zero Temperature Sensor (Celsius)	Reset the temperature sensor to Celsius.
≫ °F	Zero Temperature Sensor (Fahrenheit)	Reset the temperature sensor to Fahrenheit.

#### Data Logging – Investigator Levels 1-3

	Light Sensor	Collect light sensor data.
R	Touch Sensor	Collect a count of touch sensor presses.
<b>%</b>	Temperature Sensor	Collect temperature sensor data.
	Rotation Sensor	Collect angle sensor data.
	Sensor Adapter	Collect adapter sensor data.
<u>0</u> 00:00:01	1 sec	Set the sampling rate to 1 second between each data point.
0 ???s	Data Logging Interval	Set the sampling rate to the user-specified time interval between each data point.
2←	Touch sensor-based interval	Collect data every time the touch sensor is released.
10	10 Points	Collect 10 data points.
<u>я</u> ?	Set Points	Collect as many data points as specified.
$\mathcal{M}$	Data Logging On	Collect data during the step.



#### Data Logging – Investigator Level 4

	Investigator Sub-menu	Icons in this sub-menu control the operation of the data logging functions of the RCX.
<b>S</b>	Initialize Light Sensor Logging	Initialize light sensor to take data and configures data logging settings. Default settings: sensor on input Port 1, data set to the red set.
S?	Initialize Touch Sensor Logging	Initialize touch sensor to take data and configures data logging settings. Default settings: sensor on input Port 1, data set to the red set.
<b>X</b>	Initialize Temperature Sensor Logging	Initialize temperature sensor to take data and configures data logging settings. Default settings: sensor on input Port 1, data set to the red set.
<b>S</b>	Initialize Rotation Sensor Logging	Initialize rotation sensor to take data and configures data logging settings. Default settings: sensor on input Port 1, data set to the red set.
	Initialize Clicks Sensor Logging	Initialize touch sensor to take number of clicks as data and configures data logging settings. Default settings: sensor on input Port 1, data set to the red set.
24	Initialize Container Logging	Initialize a Container to take data and configures data logging settings.
Ċ	Initialize Timer Logging	Initialize a Timer to take data and configures data logging settings.
64	Start Data Logging	Start capturing or logging data.
6	Stop Logging	Stop capturing or logging data.
9v	Resume Logging	Resume capturing or logging data.
5	Start Data Logging With Clicks	Start capturing or logging data and clicks each time a data point is taken.

#### **Data Logging Modifiers**

	Sample One Tenth Sec	Capture data every one tenth of a second.
	Sample One Minute	Capture data every minute.
	Sample One Hour	Capture data every hour.
	Touch Sampling	Capture data every time the touch sensor is pressed.
٩	Red Data Set	Identify the location where data is stored.
	Free Sample With Time Stamp	Capture data every time you write on the data set and mark the data with the time.



#### **Compute Tools 1**

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$\triangleright$	Add	Add two values.
$\geq$	Subtract	Subtract one value from another.
$\geqslant$	Multiply	Multiply two values together.
$ \geq $	Divide	Divide one value by another.

#### **Compute Tools 3**

$\sim$	Maxima	Plot the maximum value of each data set in the selected bin.
$\sim$	Minima	Plot the minimum value of each data set in the selected bin.
$\sim$	Mean	Plot the mean value of each data set in the selected bin.
	Standard Deviation	Plot the standard deviation of each data set in the selected bin.
$\sim$	No Change	Plot all the data sets in the selected bin.
$\sim$	Slope	Plot the value of the slope for each data set in the selected bin.
∫dt	Integrate	Plot a line that is the integral for each set of data in the selected bin.
$\frac{d}{dt}$	Differentiate	Plot a line that is the derivative for each data set in the selected bin.
K.	Average Line	Plot one line that is the average of all data sets in the selected bin.
	Fit Line	Plot a linear best fit curve for each data set in the selected bin. The linear equations are also shown.



#### **Compute Tools 4**

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View All	Show the data set in any bin. Default: red bin.
Extract	Separate the X and Y coordinates of a data set in two arrays.
Combine	Combine the X and Y values into a plot.
Combine Bins	Combines two plots together.
XY Plot	Add the data set defined by the X and Y numbers to an existing bin.
Bin Plots	Put the contents of a plot into a bin.
Well Time	Find the time the measured value in a data set is below a given threshold.
Peak Time	Find the time the measured value in a data set exceeds a given threshold.
Threshold	Extract the measured values in a data set when they are between two thresholds.
Fit Curve	Fit a curve to the specified data set.
Fit Exponential	Fit an exponential to the specified data set.
Histogram	Give a histogram for each data set.
Bin Modifiers	Select the bin for the data set.

#### Events

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*	Event Sub-menu	Icons in this sub-menu allow you to set up programming based on events. More information is available at http://www.LEGO.com/education/mindstorms.
	Start Monitoring for an Event	Start monitoring for the corresponding event(s).
	Stop Event Monitoring	Stop all event monitoring.
)*	Event Landing	This command is where the program will jump to when any event is triggered.



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Set Up Pressed Event	Set up an event to occur when the touch sensor is pressed.
Set Up Enter High Event	Set up an event to be triggered when the value of the event source goes above the upper threshold.
Define Event	Define the settings for Enter (low, normal, and high) events.
Reset Event	Reset monitoring for an event.
Force an Event	Force the firmware to behave as if the events, whose bits are set in the calculated 16 bit value, had actually happened.
Clear All Events	Clear all 16 events.

**Events Modifiers** 

	Event Modifiers Sub-menu	Icons in this sub-menu allow you to modify the Event based program icons. More information is available at http://www.LEGO.com/education/mindstorms.
	Red Event	Wire this to an Event Definition or Monitor command to select the Red Event.
	Value of Red Event	Wire this to an Event Definition or Monitor to select the Red Timer.
$\diamondsuit$	Value of Red Upper Threshold	The value of the upper threshold for the red event.
	Value of Red Lower Threshold	The value of the lower threshold for the red event.
	Value of Red Hysteresis	The value of the hysteresis for the red event.
	Value of Red Duration	The value of the duration for the red event.

**Task Priority** 

	Task Priority Sub-menu	Monitors access control – if any task of higher priority wants control of the outputs, jump to the red access landing.
R	Task Priority	lcons in this sub-menu allow you to set priorities of different tasks in your program.
	Start Monitoring for Output Access Control	This sets the priority of any task. <b>Note:</b> 0 is the highest priority.





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Start Monitoring for Sound Access Control	Monitor access control of sound – if any task of higher priority wants control of the sound, jump to the red access landing.
Access Control Landing	This command is where the program will jump to when another task of higher priority wants control of the outputs.
Stop Access Control Monitoring	Stop access control monitoring.

#### **RCX** Communication

E	RCX Communication Sub-menu	Icons in this sub-menu specify commands used in RCX communication.
	Send Mail	Send mail to another RCX. Default - send the number 1.
Ø	Snap Image	This will tell Vision Control to snap an image and save it in the Image Folder. (This will only work with Vision Control open.)
2.50 ± 3	Set Display	Set the RCX LCD display to show a certain value.
P	Fill Mailbox	Reset the RCX mailbox to a value.
	Fill Remote Container	Set the container to a certain value on a remote RCX.
<mark>94</mark>	Start Direct RCX Communication	Start Direct Commands sent to other RCXs.
<b>P</b> I	End Direct RCX Communication	End direct communication sequence with remote RCX(s).
<mark>}1</mark>	Start Remote Program	Start remote programming to other RCXs.
	Download Remote Program	Download a sequence of commands as a program to remote RCX(s).
<b>4</b> 0	Clear Sound Buffer	This command immediately empties the sound buffer in the RCX from any and all queued tones or system sounds.
<b>4X</b>	Mute Sound	This command empties the sound buffer and ignores future sounds.
<b>()</b>	Unmute Sound	This command restarts the sound buffer to play sounds.



#### **Direct Functions**

<b>_</b> 4	Direct Functions Sub-menu	lcons in this sub-menu specify direct functions that return information to the computer.
	Memory Map	This command gives back the memory allotment within the RCX.
杰	Read Run Status	Read the Run Status of the RCX.
•?	Read Tower Power	Read the transmitter power on the RCX.
D	RCX Tower Power	Set the transmitter power of the RCX.
• ↓?	RCX Battery Power	Check the battery level of the RCX. Outputs a value between 0 and 9.

Advanced

000	Advanced Sub-menu	Icons in this sub-menu allow you to program specific types of coding. More information is available at http://www.LEGO.com/education/mindstorms.
RCX	Begin RCX	Begins an Inventor program for the RCX.
	Begin LASM	Begins an Inventor program and shows the LASM interface.
	Begin Direct Mode	String a command in after this one to run the following commands immediately in direct mode (no download).
	Generate LASM cmd	This powerful icon allows you to enter LASM text directly. Simply wire in the line(s) of text into LASM Cmd and have the begin and end wire on either side.
?	Set Modifier Value	Set any writeable source and value.

#### **Control Lab**



**Control Lab Interface** Icons in this sub-menu allow you to write programs for the LEGO Interface B. Sub-menu

#### Scout



**Scout Commands** Icons in this sub-menu allow you to write programs for the LEGO Scout. Sub-menu



This VI closes the camera.

#### Multimedia

**Multimedia Sub-menu** 

Init Small Image

Init Internet Image

**Close Camera** 

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Grab RGB	This VI grabs a single image from an initialized camera. The color of the image is specified by Image Type.
Convert to Picture	This VI converts an image to a LabVIEW™ picture.
Convert to Array	This VI converts an image into a 2-dimensional array of rows and columns (e.g., 320 columns and 240 rows).
Get Pixel Value	This VI gets the value of the pixel located at the specified position and returns its value (either as an 8-bit number or an RGB cluster).
Advanced Video Sub-menu	The icons in this sub-menu allow you to do very advanced video processing.
Init Mic	This initializes the microphone.
Grab Sound	This VI collects one second of sound data.
Play Sound	This VI plays sound data.
Close Mic	This VI closes the microphone.
Save Sound	This VI saves sound data to a .wav file.
Frequency Analysis	This VI does a Fourier Transform on the one second of sound grabbed.

Icons in this sub-menu allow you do additional programming with video or sound. More information is available at www.LEGO.com/education/mindstorms.

This VI initializes the camera at its small setting (160x120).

This VI initializes the camera at Internet Setting (320x240).



#### Media Window

	Music Piano Player	Opens the Piano Player Window.
<b>_</b>	Play Current Song	Plays the selected song on the computer.
→I	Single Play	Plays the selected song one time.
Ð	Continuous Play	Plays the selected song in a continuous loop.
	Camera Setup	Opens the Camera Setup window.
II	Camera Pause	Freezes image in Camera window. Selecting Camera Pause again starts continual image updates.
	Save Image	Opens a save file window that allows you to name and save the current image in the Camera window to a file.



#### **Piano Player**

×	Delete Note	Deletes the selected note.
0	Record	Toggles whether or not the notes being played are kept on the scroll.
<b>B</b>	Play Current Song	Plays the current song through the computer.
	Select Computer	Selects the computer as the device which plays the notes.
	Select RCX	Selects the RCX as the device which plays the notes.
150	Тетро	Controls the tempo at which the song is played. This is displayed in beats/min.

#### **Note Articulation**

I)	Staccato	Play note for 50% of the specified duration.
	Normal	Play note for 80% of the specified duration.
	Slurred	Play note for 100% of the specified duration.

#### **Investigator Template Icons**

	Line points graph	Plots data points with a line for each data set.
4	Line graph	Plots each data set as a line.
<b>.</b>	Points graph	Plots the points of each data set.
	Bar graph	Plots each data set as a bar graph.
1.2	Numeric Table	Lists the numeric values of each data set.



#### **Investigator Graph Tools**

	The Graph Too	Is allow you to change the way your plot looks on the screen without changing
	the data itself. need to be use manipulate cur	The data sets will automatically plot with all points visible. The Graph Tools only d if you want to change the scale of your axes, zoom in or out on the graph, or rsors to determine the value of specific points in the data set.
<u>الخار</u>	Autoscale X Data	Set the scale of the x-axis of the graph to match the range of the data set.
ЦY	Autoscale Y Data	Set the scale of the y-axis of the graph to match the range of the data set.
Ш	Lock Autoscaling	Turns on or off the x or y autoscale feature. Right is autoscaling on. Left is autoscaling off.
X.XX	Format and Precision Control	Allows you to set the format (linear or logarithmic scales) and the decimal place precision of the x and y scales.
<b>∀. Ÿ<u>Ÿ</u></b>		
+	Standard Operate Mode	Graph Tools open in the standard operate mode.
æ	Zoom Button	Opens a window with multiple options for zooming in or out on the graph.
	Pan Button	Allows you to "grab" the plot and move it within the graph area.
	Enlarge Button	Opens a screen-sized graph window with two cursors. Clicking and dragging the cursors over points from the data set shows the actual values. It also lets you identify which lines go with each data set.
Vision Ce	nter	
	Select Camera	Selects which camera to use.
R	Define Sensor	Defines a sensor for the camera to use.
■¢	Save Picture	Saves the current image to a bitmap file.
	Connection Speed	Toggles between No Connection with the RCX, Slow Connection, and Fast Connection.
PLANE	Plane	Selects which color plane to view the image in. Selecting a container will allow

